

Module Aligner 3D



Program version	BASIC	2D PRO	3D PRO	LAB	OMS
Availability	✗	✗	📦	📦	📦

✗

not included

📦

included by

📦

optionally

📦

included

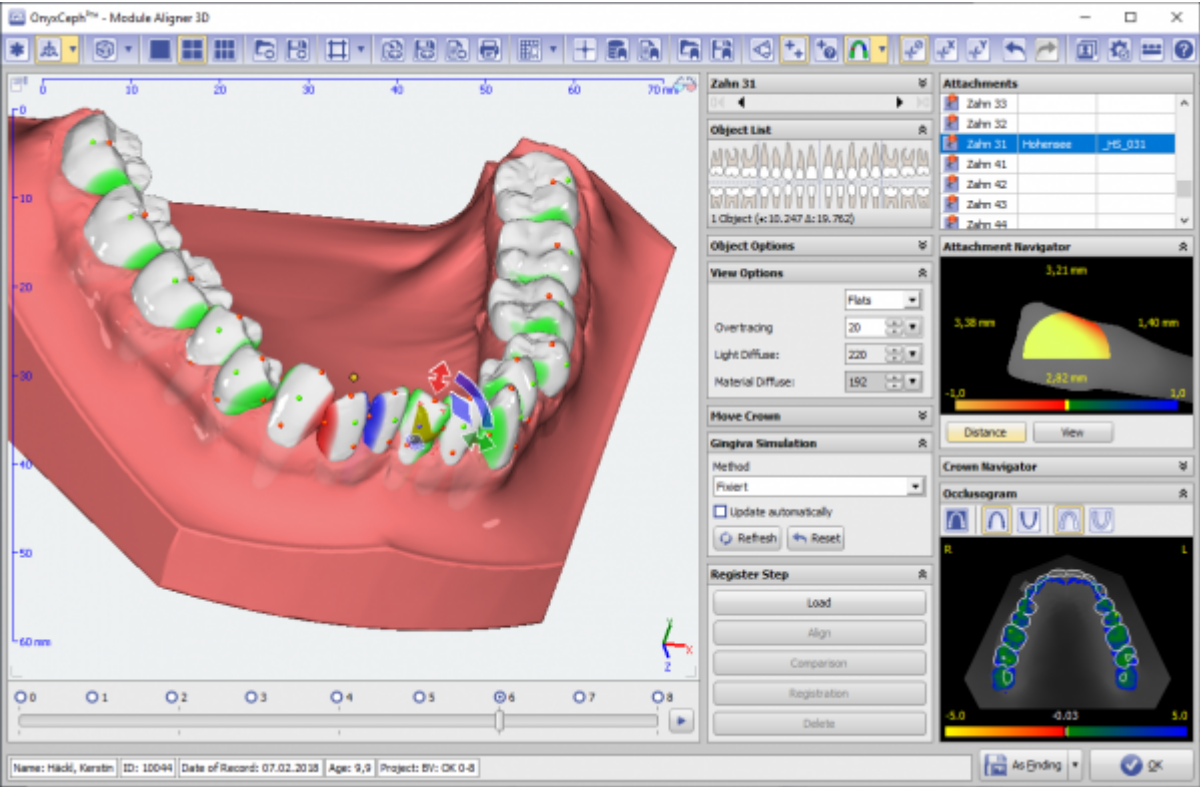
The Aligner 3D module can be used to virtually plan treatment increments (stages and steps) between the initial situation and the target situation set up in the Aligner module itself or in the [V.T.O.3D](#) module. Self-defined crown-specific limits for all components of the tooth movement including IPR can be used to define the stages and steps. To support individual movements, provided or self-constructed attachments can be applied manually or using a set of rules.

The Aligner module provides software tools for planning virtual tooth movements based on image or scan data and exporting modified dental arches. The user must ensure that the source data and the manipulations and calculations performed on it are suitable for the intended use in the context of the intended treatment measures. The user must ensure that the source data and the manipulations and calculations performed on it are suitable for the intended use in the context of the intended treatment measures. In accordance with the intended purpose, clinical decisions cannot be motivated exclusively or even mainly on evaluation results provided by the software.














First Steps

1. Define planning target on timeline or use [V.T.O.3D](#)-finding
2. Optionally add attachments using the point list
3. Add intermediate steps on timeline, e.g. acc. to motion limits
4. Check and adjust intermediate steps
5. Save as project, export aligner series using the object list

Module user interface



Links

	Request Quick Reference Guide Module Aligner
	Panel Auxilliary Objects
	Use Multiple Attachments per Crown
	Digital Aligner Planning: Software Requirements
	Extended Staging
	Staging-Editor
	Aligner Manufacturing Integration
	Positive Aligners
	Module Handout Aligner 3D
	Alignertherapie im Eigenlabor (in German)
	Positively seen
	Serial Export
	New Features: Staging etc.
	Attachment Designer

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